# **Equivalence of**  $D_{ijkl}$  **to**  $Q_{ijkl}$

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### **Abstract**

The author of this article introduced two important physical variables,  $K_{iikl}$  in Eq. 10 of Ref. 1

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and  $D_{ijkl}$ , which defines the ultrasonic equation of motion as

$$
D_{ijkl} \equiv \frac{1}{2} (B_{ijkl} + B_{iljk}) = \sigma_{kl} \delta_{ij} + \frac{1}{2} (C_{ikjl} + C_{iljk}), \text{ where}
$$
  
\n
$$
B_{ijkl}(\mathbf{X}) = (\frac{\rho_X \partial^2 U}{\partial (x_k / x_l) \partial (x_l / x_k)})_{s;x} = \delta_{ik} \sigma_{jl} + C_{ijkl}(X), \text{ in Eq. (19-22) of Ref. 2,}
$$
  
\n
$$
\rho_X \ddot{u}_i = D_{ijkl} \frac{\partial^2 u_j}{\partial x_k \partial x_l} \text{ in Eq. 70 of Ref. 1.}
$$

This article shows that  $D_{ijkl}$  is equivalent to  $K_{ijkl}$ .

*Keywords*: Equivalence of  $D_{ijkl}$  to  $K_{ijkl}$ 

### **I. Introduction**

 At first, we introduce three deformation states characterized as indices a, X, and i, where index a represents an undeformed stress-free state, index X characterizes a static finite deformation state from the undeformed state a, and index i represents a small deformation state superposed on the finite deformation state X by a travelling ultrasonic wave. Two variables  $\alpha_{ij}$  and  $\beta_{ij}$  are defined as

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$$
\alpha_{ij} \equiv \frac{\partial x_i}{\partial X_j} \qquad \beta_{ij} \equiv \frac{\partial X_i}{\partial x_j} \qquad (1)
$$

Introduce now displacement gradient  $u_{ij}$  defined as

$$
u_{ij} \equiv \frac{\partial u_i}{\partial X_j}.
$$
 (2)

Then,

$$
\epsilon_{ij} = \frac{1}{2} (u_{ij} + u_{ji}) = \frac{1}{2} (\alpha_{ij} + \alpha_{ji} - 2\delta_{ij}), \qquad (3)
$$

We also define in the initial state **X** the effective elastic stiffness  $K_{ijkl}$  and the effective elastic compliance  $Q_{ijkl}$  of the second order, which indicate the measure of material strength in the initial state, as [see Ref. 1]

$$
K_{ijkl} = \left(\frac{\partial \sigma_{ij}}{\partial \epsilon_{kl}}\right)_X = C_{ijkl}(X) - \sigma_{ij}(X)\delta_{kl} + \frac{1}{2} \left(\delta_{jk}\sigma_{il}(X) + \delta_{il}\sigma_{jk}(X) + \delta_{ik}\sigma_{jl}(X)\right),\tag{4}
$$

$$
\begin{bmatrix}\nC_{11} + \sigma_1 & C_{12} - \sigma_1 & C_{13} - \sigma_1 & C_{14} & C_{15} + \sigma_5 & C_{16} + \sigma_6 \\
C_{11} - \sigma_2 & C_{22} + \sigma_2 & C_{23} - \sigma_2 & C_{24} + \sigma_4 & C_{25} & C_{26} + \sigma_6 \\
C_{13} - \sigma_3 & C_{23} - \sigma_3 & C_{33} + \sigma_3 & C_{34} + \sigma_4 & C_{35} + \sigma_5 & C_{36} \\
C_{14} - \sigma_4 & C_{24} & C_{34} & C_{44} + (\sigma_2 + \sigma_3)/2 & C_{45} + \sigma_6/2 & C_{46} + \sigma_5/2 \\
C_{15} & C_{11} + \sigma & C_{35} & C_{45} + \sigma_6/2 & C_{44} + (\sigma_2 + \sigma_3)/2 & C_{56} + \sigma_4/2 \\
C_{16} & C_{26} & C_{36} - \sigma_6 & C_{46} + \sigma_5/2 & C_{56} + \sigma_4/2 & C_{44} + (\sigma_2 + \sigma_3)/2\n\end{bmatrix}
$$
\n(5)

In the above Eqs. 4 and 5,  $K_{ijkl}$  or  $[K_{\alpha\beta}]$  can be conveniently obtained by measuring the Cauchy stresses  $\sigma_i$  ( $i = 1,2$  6), measurements of which in uniaxial loading case are described in detail [see Ref. 3], and the second-order elastic stiffness constants  $C_{ij}$  (i, j = 1,2, 6), which can be accurately obtained by ultrasonic wave-speeds measurements [see Ref. 2].

It is noted that full symmetry relations as found in  $C_{ijkl}$  are lost in  $K_{ijkl}$  and  $Q_{ijkl}$ .  $K_{ijkl}$  obey the relations  $K_{ijkl} = K_{klij} = K_{ijlk}$  along with

$$
K_{ijkl} - K_{klij} = \delta_{ij}\sigma_{kl} - \delta_{kl}\sigma_{ij}
$$
\n(6)

$$
K_{ijkl}Q_{klmn} = \frac{1}{2}(\delta_{im}\delta_{jn} + \delta_{in}\delta_{jm}), \qquad K_{\alpha\beta}Q_{\beta\gamma} = \delta_{\alpha\gamma}.
$$
 (7)

Here isothermal compressibility  $x^T(X)$  is introduced as

$$
x^T(\mathbf{X}) \text{ (Compressibility)} = -\frac{1}{V} \left( \frac{\partial V}{\partial P} \right)_T = -\left( \frac{\partial J}{\partial P} \right)_T, \tag{8}
$$

where *p* and *J* denote the hydrostatic pressure and the Jacobian, respectively.

$$
x^T(\mathbf{X}) = -\left(\frac{\partial J}{\partial P}\right)_{T;\mathbf{X}} = Q_{iikk}(\mathbf{X})
$$

 In a stressed state Ref. 2 defines in Eq. (19.22) the isentropic elastic stiffness coefficients  $B_{ijkl}(\mathbf{X})$  as

$$
B_{ijkl}(\mathbf{X}) = \left(\frac{\rho_X \partial^2 U}{\partial (x_k/X_l) \partial (x_l/X_k)}\right)_{\mathbf{S};\mathbf{X}} = \delta_{ik} \sigma_{jl} + C_{ijkl}(X),\tag{9}
$$

where *U* is the internal energy of deformation of a material. Note that

$$
B_{ijkl} = T_{jl} \, \delta_{ik} + C_{ijkl}; \quad B_{klij} = B_{ijkl}; \quad B_{ijkl} \neq B_{jikl}; \quad B_{ijkl} \neq B_{ijkl} \quad . \tag{10}
$$

At **X** let  $D_{ijkl} \equiv \frac{1}{2}$  $\frac{1}{2}(B_{ijkl} + B_{iljk}) = \sigma_{kl}\delta_{ij} + \frac{1}{2}$  $\frac{1}{2}(C_{ikjl} + C_{iljk}).$  (11)

Then,

$$
D_{ijkl}(\mathbf{X}) - D_{klij}(\mathbf{X}) = K_{ijkl}(\mathbf{X}) - K_{klij}(\mathbf{X}) = \delta_{ij}\sigma_{kl} - \delta_{kl}\sigma_{ij},
$$
\n(12)

which is known as Huang's conditions.

Ultrasonic equation of motion at **X** is expressed as

$$
\rho_X \ddot{u}_i = D_{ijkl} \frac{\partial^2 u_j}{\partial x_k \partial x_l} \tag{13}
$$

## **II. Relation between**  $K_{ijkl}$  **and**  $D_{ijkl}$

$$
D_{ijkl} = \delta_{ij}\sigma_{kl} + (1/2)(C_{ikjl} + C_{iljk})
$$
 (14)

$$
D_{ikjl} = \delta_{ik}\sigma_{jl} + (1/2)(C_{ijkl} + C_{iljk})
$$
\n(15)

$$
D_{ijkl} = \delta_{il}\sigma_{jk} + (1/2)(C_{ijkl} + C_{ikjl})
$$
 (16)

Eq. 15 minus Eq. 14 plus Eq. 16 results in

$$
D_{ikjl} - D_{ijkl} + D_{iljk} = \delta_{ik}\sigma_{jl} - \delta_{ij}\sigma_{kl} + \delta_{il}\sigma_{jk} + C_{ijkl}
$$
\n(17)

Therefore,  $C_{ijkl} = D_{ikjl} - D_{ijkl} + D_{iljk} + \delta_{ij}\sigma_{kl} - \delta_{ik}\sigma_{jl} + \delta_{il}\sigma_{jk}$  (18)

$$
K_{ijkl} = C_{ijkl} - \delta_{ij}\sigma_{kl} + (1/2)(\delta_{ik}\sigma_{jl} + \delta_{jk}\sigma_{il} + \delta_{il}\sigma_{jk} + \delta_{ik}\sigma_{jl})
$$
  

$$
= \frac{1}{2}(D_{ikjl} + D_{iljk} + D_{jkil} + D_{jlik}) - D_{klij}
$$
 (19)

# **III.** Equivalence of  $D_{ijkl}$  to  $K_{ijkl}$

Now we consider four cases of ijkl indices of D.

Case 1. Three indices of i,j,k, & lare equal, i.e.,  $i=j=k$  or  $i=j=l$  or  $i=k=l$ .

Then, 
$$
K_{ijkl} = D_{ijkl}
$$

Case 2. Two indices are equal. i.e., i=j or k=l, but  $i \neq k$ 

Then, 
$$
K_{ijkl} = 2D_{ikjl} - D_{klij}
$$

Case 3. Two indices are equal, i.e., (i=k & j=l) or (i=l & j=k), but (i $\neq$  j & k  $\neq$  l)

Then,  $K_{ijkl} = (D_{ikil} + D_{ilik})/2$ 

Case 4.  $((i\neq j \& k \neq l) \& i = k \& j \neq l$  or  $(i\neq k \& j = l)$ ) or  $(i = l \& j \neq k)$  or  $(i\neq l \& j = k)$ 

Then,  $K_{ijkl} = (D_{i l i k} + D_{ik i l})/2$ 

In all cases either  $K_{ijkl} = D_{ijkl}$  or  $K_{ijkl}$  is a linear combination of two D's coefficients.

### **IV. Conclusion**

This work demonstrates the equivalence of  $D_{ijkl}$  to  $K_{ijkl}$ , which indicates the measure of material strength in the initial state X.

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